

# QR Factorization in Parallel

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December 19, 2012

# What is a QR Decomposition?

Any matrix  $A \in \mathbb{C}^{m \times n}$  has a QR factorization,  $Q \in \mathbb{C}^{m \times m}$  a unitary orthogonal matrix and  $R \in \mathbb{C}^{m \times n}$  an upper triangular matrix. Since  $Q$  is unitary

$$\det(Q) = \pm 1 \quad \text{and} \quad Q^*Q = I.$$

If  $m \geq n$  then  $R$  has the following form,

$$R = \begin{bmatrix} \hat{R} \\ 0 \end{bmatrix}.$$

The factorization

$$A = \hat{Q}\hat{R}$$

$\hat{Q} \in \mathbb{C}^{m \times n}$  and  $\hat{R} \in \mathbb{C}^{n \times n}$  is called the reduced QR factorization.

# Why QR?

QR decompositions can be used for many things:

- Fundamental Part of QR algorithm

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**Algorithm 1.1** The QR Algorithm (without shifts)

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$$A^{(0)} = A$$

**for**  $k = 1, 2, \dots$  **do**

$$Q^{(k)}R^{(k)} = A^{(k-1)}$$

$$A^{(k)} = R^{(k)}Q^{(k)}$$

**end for**

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- Least Squares Problem
- Other Matrix Factorizations
- Finding Eigenvalues and Eigenvectors of  $A$

# Navie QR Factorization

Three Different Ways to perform QR Factorization:

## 1. Gram-Schmidt

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## 2. Givens Rotations

- Zeros out one element at a time.
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## 3. Householder Reflections

- Zeros out a whole column a time.
- We used this algorithm as a base for our code.

# Householder Reflections

Householder Reflections are special unitary matrices  $P_i$  such that,

$$\begin{pmatrix} x & x & x \\ x & x & x \\ x & x & x \\ x & x & x \end{pmatrix} \xrightarrow{P_1} \begin{pmatrix} x & x & x \\ 0 & x & x \\ 0 & x & x \\ 0 & x & x \end{pmatrix} \xrightarrow{P_2} \begin{pmatrix} x & x & x \\ 0 & x & x \\ 0 & 0 & x \\ 0 & 0 & x \end{pmatrix} \xrightarrow{P_3} \begin{pmatrix} x & x & x \\ 0 & x & x \\ 0 & 0 & x \\ 0 & 0 & 0 \end{pmatrix}$$

$A$                        $P_1A$                        $P_2P_1A$                        $P_3P_2P_1A$

where

$$P_i = I - 2 \frac{v_i v_i^t}{v_i^t v_i}.$$

and

$$v_i(k) = \text{sign}(a_{ii}) \|A_{k,i}\|_2 e_1 + A_{k,i} \quad \text{if } i \geq k \quad \text{else } v_i(k) = 0$$

# QR Factorization via Householder Reflections

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## Algorithm 2.1 Householder QR Factorization

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```

for  $k = 1$  to  $n$  do
   $x = A_{k:m,k}$ 
   $v_k = \text{sign}(x_1) \|x\|_2 e_1 + x$ 
   $v_k = v_k / \|v_k\|_2$ 
   $A_{k:m,k:n} = A_{k:m,k:n} - 2v_k(v_k^* A_{k:m,k:n})$ 
end for

```

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Notice that this algorithm does NOT produce both the  $Q$  and the  $R$ . To get the  $Q$  we would need to multiply all of the Householder Reflections together.



# WY Representation of Q

The WY representation of  $Q$  writes the product of householder reflection matrices

$$Q_k = P_1 \cdots P_k$$

in the form

$$Q_k = I + W_k Y_k^T$$

where  $W_k$  and  $Y_k$  are  $n$  by  $k$  matrices and

$$P_i = I - 2 \frac{v_i v_i^T}{v_i^T v_i}.$$

is a rank one update.

## WY continued

Then

$$Q_k^T A = (I + Y_k W_k^T) A = A + Y_k W_k^T A$$

and

$$\begin{aligned} Q_k &= Q_{k-1} P_k = (I + W_{k-1} Y_{k-1}^T)(I - \beta v_k v_k^T) \\ &= I + W_{k-1} Y_{k-1}^T - \beta Q_{k-1} v_k v_k^T \\ &= I + (W_{k-1} \quad -\beta Q_{k-1} v_k) \begin{pmatrix} Y_{k-1}^T \\ v_k^T \end{pmatrix} \\ &= I + (W_{k-1} \quad -\beta Q_{k-1} v_k) (Y_{k-1} \quad v_k)^T \\ \Rightarrow W_k &= (W_{k-1} \quad -\beta Q_{k-1} v_k) \\ \text{and } Y_k^T &= \begin{pmatrix} Y_{k-1}^T \\ v_k^T \end{pmatrix}. \end{aligned}$$

## Simple 3x3 WY example

Given a matrix  $A$ ,

$$A = \begin{pmatrix} 3.83 & 9.15 & 3.86 \\ 8.88 & 7.93 & 4.92 \\ 7.77 & 3.35 & 6.49 \end{pmatrix}$$

Step 1: Compute  $v_1$  where  $a_1$  is the first column of  $A$ ,

$$\begin{aligned} v_1 &= a_1 + \text{sign}(a_{11})e_1 \|a_1\|_2 \\ &= \begin{pmatrix} 3.83 \\ 8.88 \\ 7.77 \end{pmatrix} + \begin{pmatrix} 12.39118 \\ 0 \\ 0 \end{pmatrix} \\ &= \begin{pmatrix} 16.22118 \\ 8.86 \\ 7.77 \end{pmatrix} \end{aligned}$$

## Simple 3x3 WY example continued...

Step 2: Update  $v_1$  and compute  $w_1 = -2v_1$ ,

$$\begin{aligned} v_1 &= v_1 / \|v_1\|_2 \\ &= \frac{1}{20.04991} \begin{pmatrix} 16.22118 \\ 8.86 \\ 7.77 \end{pmatrix} \\ &= \begin{pmatrix} 0.80903 \\ 0.44189 \\ 0.38753 \end{pmatrix} \end{aligned}$$

Insert into  $W$  and  $Y^t$  matrices,

$$W = \begin{pmatrix} -1.61807 & 0.0 & 0.0 \\ -0.88379 & 0.0 & 0.0 \\ -0.77506 & 0.0 & 0.0 \end{pmatrix}, Y^t = \begin{pmatrix} 0.80903 & 0.44189 & 0.38753 \\ 0.0 & 0.0 & 0.0 \\ 0.0 & 0.0 & 0.0 \end{pmatrix}$$

## Simple 3x3 WY example continued...

Step 3: Compute  $Q_1$  and  $Q_1^t$ :

$$\begin{aligned} Q_1^t &= (I + WY^t)^t \\ &= \begin{pmatrix} -0.30909 & -0.71502 & -0.62705 \\ -0.71502 & 0.60945 & -0.34249 \\ -0.62705 & -0.34249 & 0.69963 \end{pmatrix} \end{aligned}$$

Notice that

$$Q_1^t a_1 = \begin{pmatrix} -12.39118 \\ 0 \\ 0 \end{pmatrix}$$

## Simple 3x3 WY example continued...

Step 4: Update  $a_2$ ,

$$\begin{aligned} a_2 &= Q_1 a_2 \\ &= \begin{pmatrix} -10.59857 \\ -2.85687 \\ -6.10982 \end{pmatrix} \end{aligned}$$

Step 5: Compute  $v_2$  where  $x$  is the new  $a_2$  with with zeros above row 2,

$$\begin{aligned} v_2 &= x + \text{sign}(x_2)e_2\|x\|_2 \\ &= \begin{pmatrix} 0 \\ -2.85687 \\ -6.10982 \end{pmatrix} - \begin{pmatrix} 0 \\ 6.744745 \\ 0 \end{pmatrix} \\ &= \begin{pmatrix} 0 \\ 9.60161 \\ -6.10982 \end{pmatrix} \end{aligned}$$

## Simple 3x3 WY example continued...

Step 6: Update  $v_2$ , and compute  $w_2 = -2Q_1 v_2$ ,

$$\begin{aligned} v_2 &= 1/\|v_2\|_2 \\ &= \frac{1}{11.38072} \begin{pmatrix} 0 \\ 9.60161 \\ -6.10982 \end{pmatrix} \\ &= \begin{pmatrix} 0 \\ -0.84367 \\ -0.53685 \end{pmatrix} \end{aligned}$$

Insert into  $W$  and  $Y^t$  matrices,

$$W = \begin{pmatrix} -1.6180 & -1.8797 & 0.0 \\ -0.8837 & 0.6606 & 0.0 \\ -0.7750 & 0.1732 & 0.0 \end{pmatrix}, Y^t = \begin{pmatrix} 0.8090 & 0.4418 & 0.3875 \\ 0.0 & -0.8436 & -0.5368 \\ 0.0 & 0.0 & 0.0 \end{pmatrix}$$

## Simple 3x3 WY example continued...

Step 7: Compute  $Q_2$  and  $Q_2^t$ ,

$$\begin{aligned} Q_2^t &= (I + WY^t)^t \\ &= \begin{pmatrix} -0.30909 & -0.715024 & -0.62705 \\ 0.87088 & 0.052117 & -0.488690 \\ 0.382119 & -0.697154 & 0.606604 \end{pmatrix} \end{aligned}$$

Since  $A$  is square in this equation  $Q_2$  is the final  $Q$ . In general the final  $Q_k$  would be when  $k = m$ , the height of  $A$ .

Step 8: Multiply  $A$  by  $Q^t$  to get final  $R$ ,

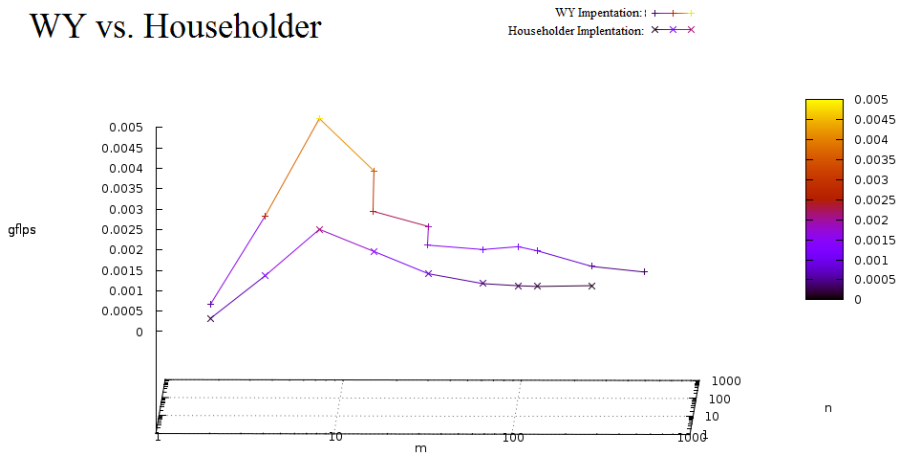
$$R = Q^t A = \begin{pmatrix} -12.391182 & -10.59872 & -8.78062 \\ 0.0 & 6.74481 & 0.446449 \\ 0 & 0 & 1.9818806 \end{pmatrix}$$

Notice that  $Q^t Q = I$ ,  $R$  is upper triangular and  $QR = A$ .



## WY Performance:

## WY vs. Householder



## Problems with WY on its own:

- 1 Best Performance at size 8 by 8.
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SOLUTION: Block matrix A - This lead to our Blocked QR version 1.

Given a matrix  $A$ :

$A_{11}$	$A_{12}$	$A_{13}$
$A_{21}$	$A_{22}$	$A_{23}$
$A_{31}$	$A_{32}$	$A_{33}$
$A_{41}$	$A_{42}$	$A_{43}$

Step 1: Preform QR factorization on green blocks.

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Step 2 and 3: Multiply yellow blocks in parallel by  $Q^t$  obtained in pervious step and update  $Q$  matrix.

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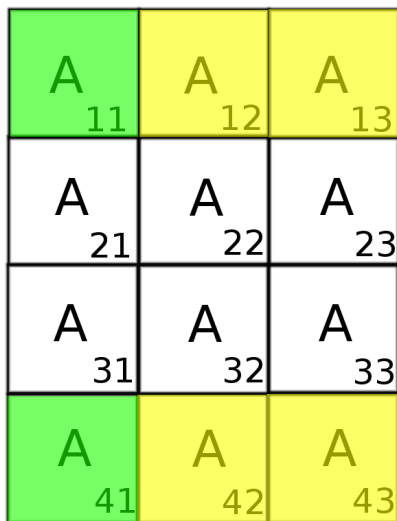
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If we have a thin and tall matrix this becomes problematic.

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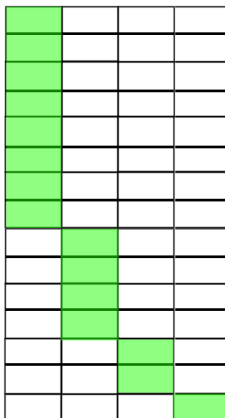
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We created Tiled QR Factorization: version 2 to fix the first problem.

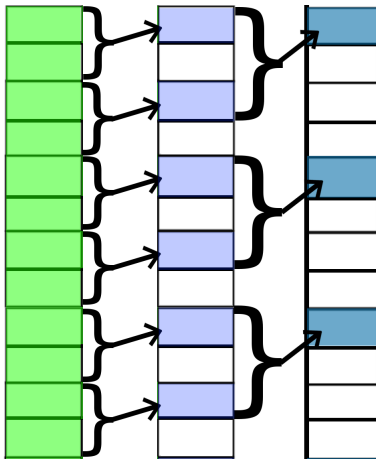
Step 1: Break up each column into sets of blocks below and including diagonal.



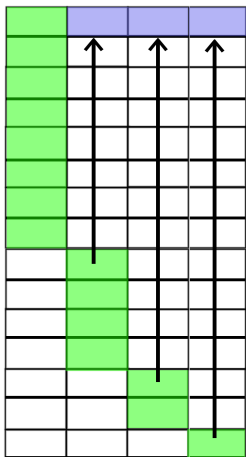
Note: This diagram denotes one column being broken up and zeroed out over multiple iterations.



Step 2: Merge each set of blocks (green sets from pervious slide) using a binary tree.



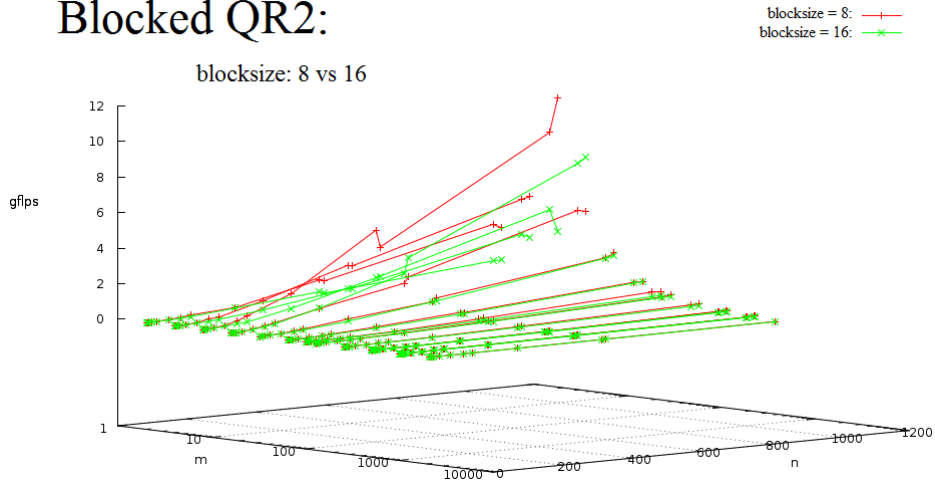
Step 3: Update root block at the after set has been merged.



## Study on block size:

## Blocked QR2:

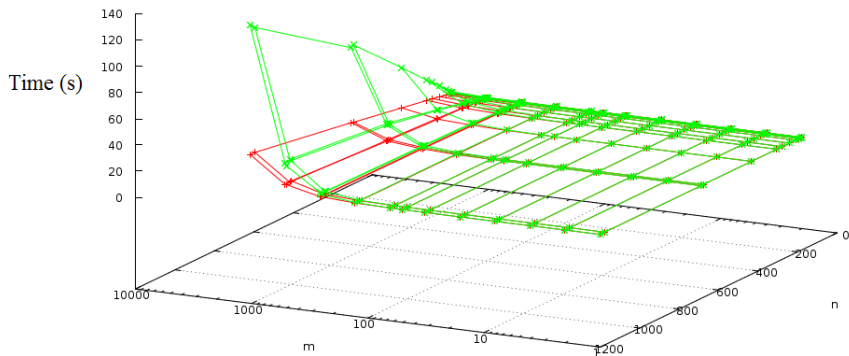
blocksize: 8 vs 16



# Comparison Study: seconds on bowery

Blocked QR:  
Version 1 vs Version 2

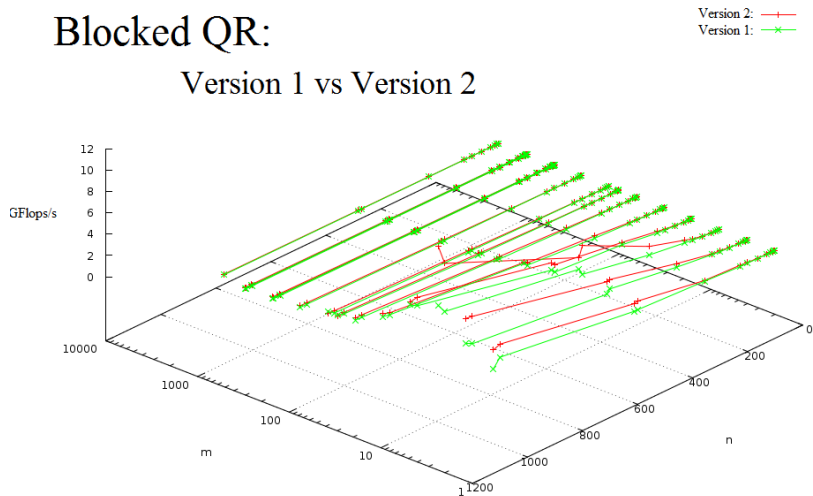
Version 2: —+—  
Version 1: —\*—



# Comparison Study: GFlops per second on bowery

## Blocked QR:

### Version 1 vs Version 2



## Futher Work:

- Utilize L2 Cahce sizes by adding another layer of blocking.

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- Figure out a way to avoid bottlenecks that appear in Version 2.