Numerical Methods (CS 357) Worksheet

Problem 1. Value of the condition number

Consider the matrix

$$A = \begin{pmatrix} 5 & 0\\ 0 & 20 \end{pmatrix}.$$

What's the value of the 2-norm-based condition number of A?

Problem 2. Problems with Rank Finding

Which of the following is a problem with finding the rank of a number of vectors computationally using pivoted Gaussian elimination?

- (A) Infeasibly expensive (in terms of computational work)
- (B) May break down if near-zeros occur in input
- (C) Answer brittle/poorly defined due to rounding errors
- (D) Only works for 'square' sets of vectors, i.e. sets of n vectors of length n

Problem 3. Computational expense of solving many linear systems

Suppose you have both the inverse A^{-1} and a *PLU* factorization of an $n \times n$ matrix. What is true about the computational expense of finding the solution of k linear systems $Ax_i = b_i$ (i = 1, ..., k) using both of these methods?

- (A) Using the inverse is asymptotically cheaper $(n^2 \text{ vs } n^3)$
- (B) Asymptotically, the two methods have the same computational cost $(n^2 \text{ and } n^2)$
- (C) Asymptotically, the two methods have the same computational cost $(n^3 \text{ and } n^3)$
- (D) Using LU is asymptotically cheaper $(n^3 \text{ vs } n^2)$

Problem 4. Nullspace Finding

Given a LU factorization PA = LU of a matrix A, we know that the nullspace is preserved by this facatorization as N(PA) = N(U). Which of the following are true statements?

- (A) The nullspace of A can be "read off" from U with little (at most linear in n) computational work.
- (B) Having an LU factorization of A does not help significantly with computing the nullspace of A.
- (C) Computing the nullspace is inherently brittle because of rounding error.
- (D) Matrices in echelon form do not have a nullspace.