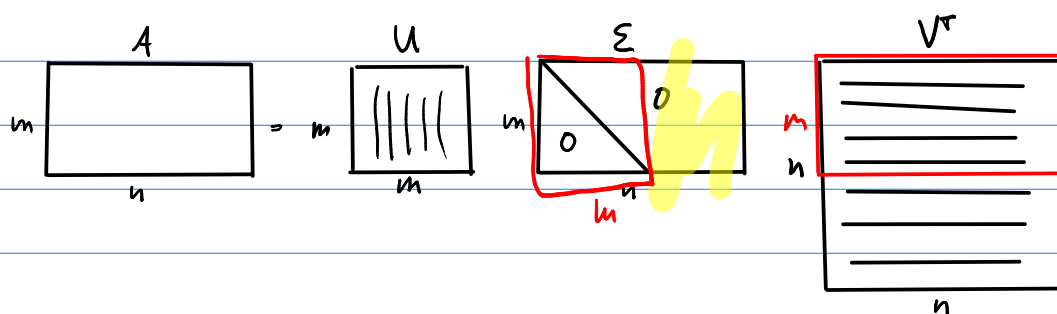
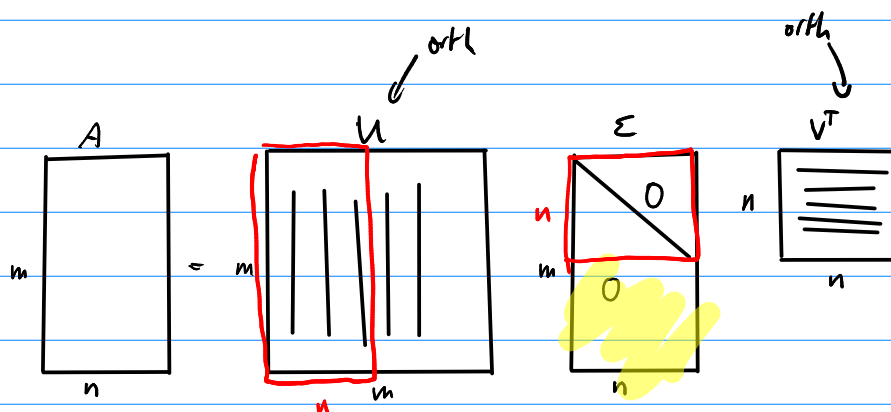


Midterm 2: April 9

Outline: SVD

- low-rank approx
- computing norm / cond
- PCA
- SVD \rightarrow least squares

What was the SVD again? And: is there a reduced form?



e

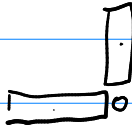
What's another way of writing the SVD?


Starting from $A = U \Sigma V^T = \begin{pmatrix} | & & | \\ u_1 & \dots & u_m \\ | & & | \end{pmatrix} \begin{pmatrix} \sigma_1 & & 0 \\ & \ddots & \\ 0 & & \sigma_n \\ & & & 0 \end{pmatrix} \begin{pmatrix} - & v_1 & - \\ | & & | \\ & \vdots & \\ - & v_n & - \end{pmatrix}$

$$A = \sigma_1 u_1 v_1^T + \dots + \sigma_n u_n v_n^T$$

outer product

inner :


 $x^T y$


 $x y^T$

If $\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_n \geq 0$, we can use the above form of A, but stop early:

$$A \approx \sigma_1 u_1 v_1^T + \dots + \sigma_k u_k v_k^T + \dots + \sigma_n u_n v_n^T$$

What do the singular values mean? (in particular the first/largest one)

$$\|A\|_2 = \max_{\|x\|_2=1} \|Ax\|_2 = \max_{\|y\|_2=1} \|\Sigma y\|_2 = \sigma_1$$

Say I want just a rank-1 approximation of A:

$$A_1 = \sigma_1 u_1 v_1^T \quad \leadsto \quad \|A_1\|_2 = \sigma_1$$

$$= U \begin{pmatrix} \sigma_1 & 0 \\ 0 & 0 \end{pmatrix} V^T$$

How expensive is it to compute the SVD?

$$O(n^3)$$

So why bother with the SVD if it is so expensive? I.e. what makes the SVD special?

$$A = \sigma_1 u_1 v_1^T + \sigma_2 u_2 v_2^T + \dots + \sigma_n u_n v_n^T$$

$\sigma_1 \geq \sigma_2 \geq \sigma_3 \geq \dots \geq \sigma_n \geq 0$

$$A_k = \sigma_1 u_1 v_1^T + \dots + \sigma_k u_k v_k^T \quad (k \leq n)$$

Then $\|A - B\|_2$ where $\text{rank}(B)=k$ is minimized by A_k .

("Eckart-Young theorem")

A_k is called the rank-k best-approximation

What is the Frobenius norm of a matrix?

$$\|A\|_F = \sqrt{a_{11}^2 + a_{12}^2 + \dots + a_{1n}^2 + a_{21}^2 + \dots + a_{nn}^2}$$

⚠ not really a matrix norm in our sense--
as in, not produced by any vector norm

How about rank-k best-approximation in the Frobenius norm?

Then $\|A - B\|_F$ where $\text{rank}(B)=k$ is minimized by A_k .

(~~"Eckart-Young theorem"~~)

A_k is called the rank-k best-approximation

9

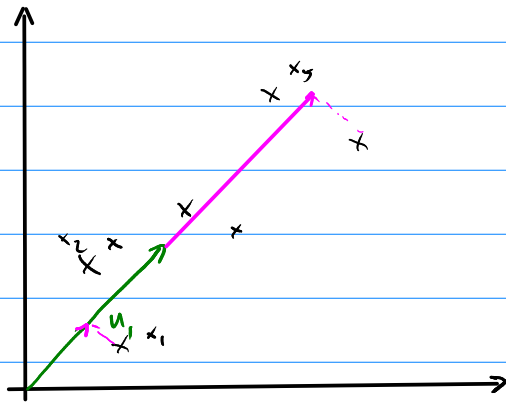
Applications of the SVD

(1) Rank-k approximation

Rank-1 approximation

$$X = \left(\begin{array}{c|c|c} | & \dots & | \\ x_1 & & x_n \\ \hline \end{array} \right) \}^2$$

$\underbrace{\hspace{10em}}_n$



break down by columns

$$\|X - X_1\|_F^2 = \sum_i \|\vec{x}_i - \sigma_1 \vec{u}_1 v_{1i}\|_2^2$$

as small as it gets

$$X = U \Sigma V^T$$

$\swarrow \quad \nwarrow \quad \nearrow$
 $2 \times 2 \quad 2 \times 2 \quad 2 \times n$
 (reduced)

$$U = \begin{pmatrix} u_1 & u_2 \\ 1 & 1 \end{pmatrix} \quad V = \begin{pmatrix} | & | \\ v_1 & v_2 \\ | & | \end{pmatrix}$$

$$X_1 = \sigma_1 u_1 v_1^T \approx X$$

$$X \approx \underbrace{\sigma_1 u_1 v_1^T}_{\text{biggy}} + \cancel{\sigma_2 u_2 v_2^T}$$

So now how about rank-k approximation?

Give an example of where rank-k approximation does something useful.

(image compression)

(2) Computing the 2-norm

$$A = U \begin{pmatrix} \sigma_1 & & \\ & \ddots & \\ & & \sigma_n \end{pmatrix} V^T$$

$$\|A\|_2 = \sigma_1$$

(3) Computing the 2-norm condition number

$$A = U \begin{pmatrix} \sigma_1 & & \\ & \ddots & \\ & & \sigma_n \end{pmatrix} V^T$$

Assume A is invertible.

$$\text{2-norm condition number} = \|A\|_2 \|A^{-1}\|_2$$

$$= \sigma_1 \|A^{-1}\|_2$$

$$A^{-1} = A^+ = V \begin{pmatrix} \frac{1}{\sigma_1} & & \\ & \ddots & \\ & & \frac{1}{\sigma_n} \end{pmatrix} U^T$$

$$= \sigma_1 \cdot \frac{1}{\sigma_n} = \frac{\sigma_1}{\sigma_n}$$

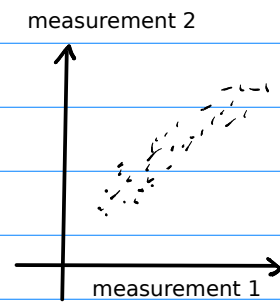
If A has a nullspace, i.e. if $\sigma_n = 0$ then the condition number is infinity.

(4) Principal Component Analysis ("PCA")

Have: a pile of "data"

More precisely: m 'measurements' from n 'trials'
each resulting in a real number

$$x_{ij} \quad i=1 \dots m \quad j=1 \dots n$$

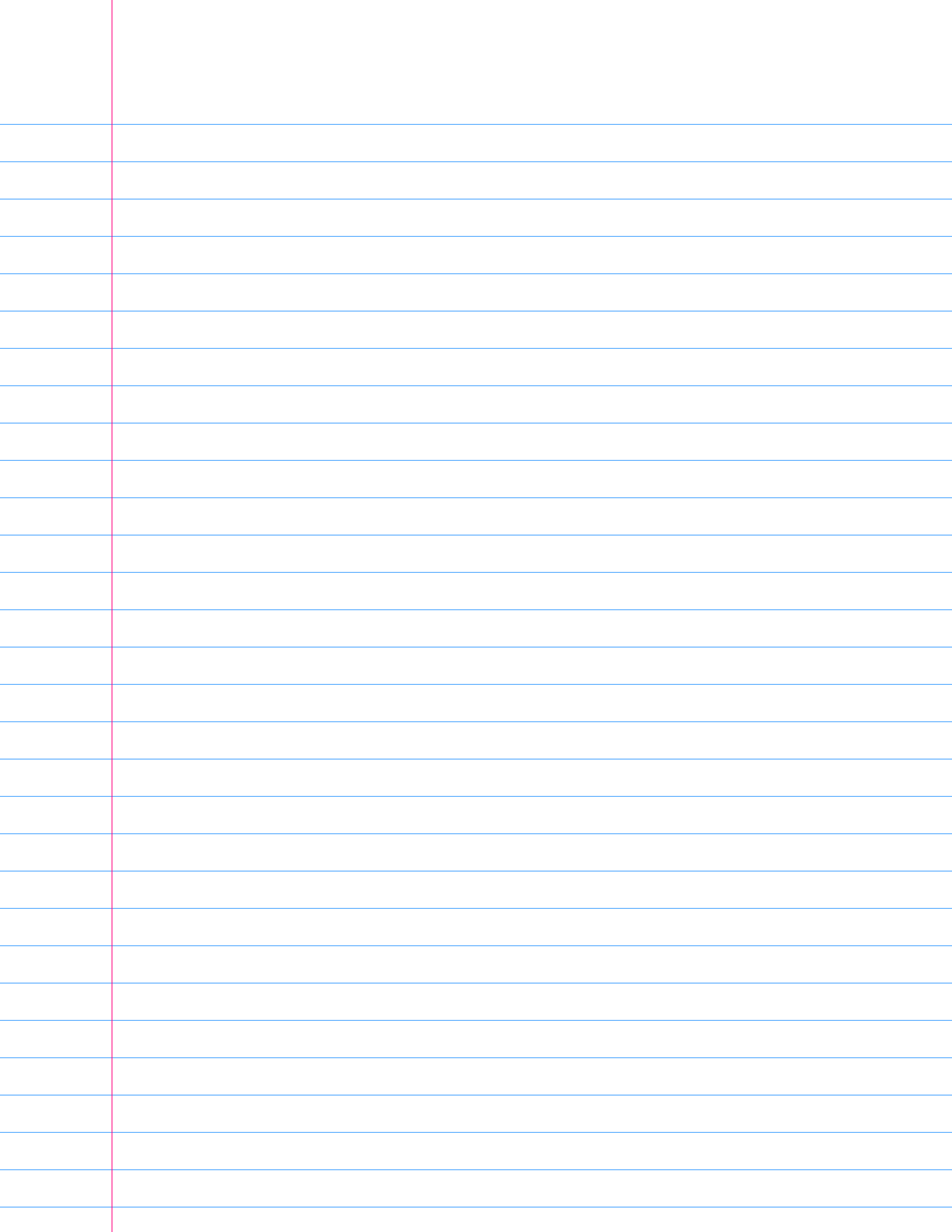


Data matrix: $X = (x_{ij}) = \begin{pmatrix} | & | & | & | & | \\ | & | & | & | & | \\ | & | & | & | & | \end{pmatrix}$
 \downarrow i: measurements
 $\xrightarrow{\hspace{1cm}}$ j: trials

How do I compute a PCA?

How do I compute a PCA? (cont'd)

(5) Least squares for underdetermined and singular systems



(6) "Total" least squares

For a given matrix A , find the vector x so that

- $\|Ax\|_2$ is minimal

- $\|x\|_2 = 1$