

CS 357: Numerical Methods

Lecture 11: QR Decomposition

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Why is orthogonality useful?

- Matrices with orthonormal columns can do special things
- $Q\mathbf{v}$ preserves the 2-norm of \mathbf{v}
- Important in Least Squares problems

Orthogonal Transformations Preserve the 2-Norm

- What is true about the columns of an orthonormal matrix Q ?
- What is QQ^T ?

Orthogonal Transformations Preserve the 2-Norm

We can show that $\|Qv\|_2^2 = \|v\|_2^2$

Orthogonal Transformations Preserve the 2-Norm

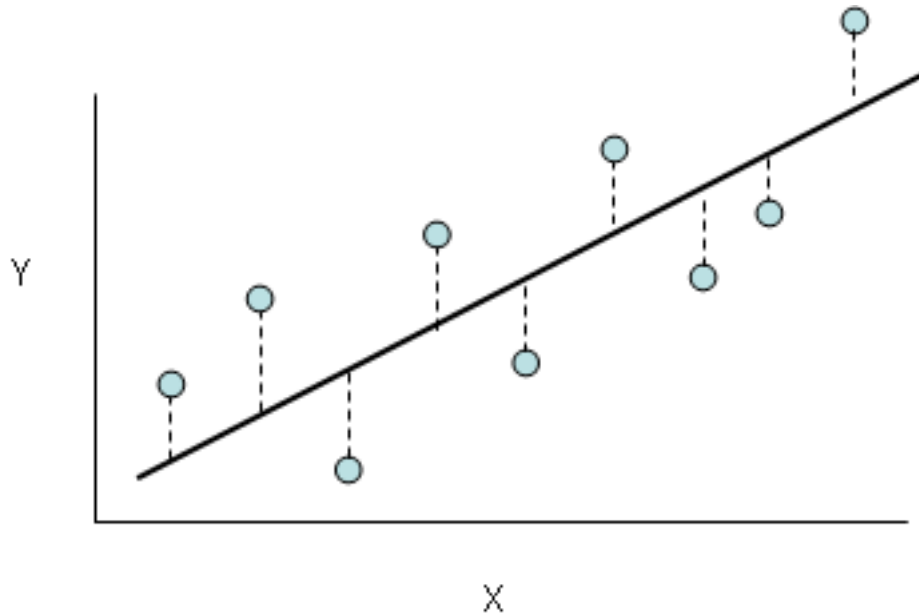
Orthogonal Transformations Preserve the 2-Norm

Orthogonal Transformations Preserve the 2-Norm

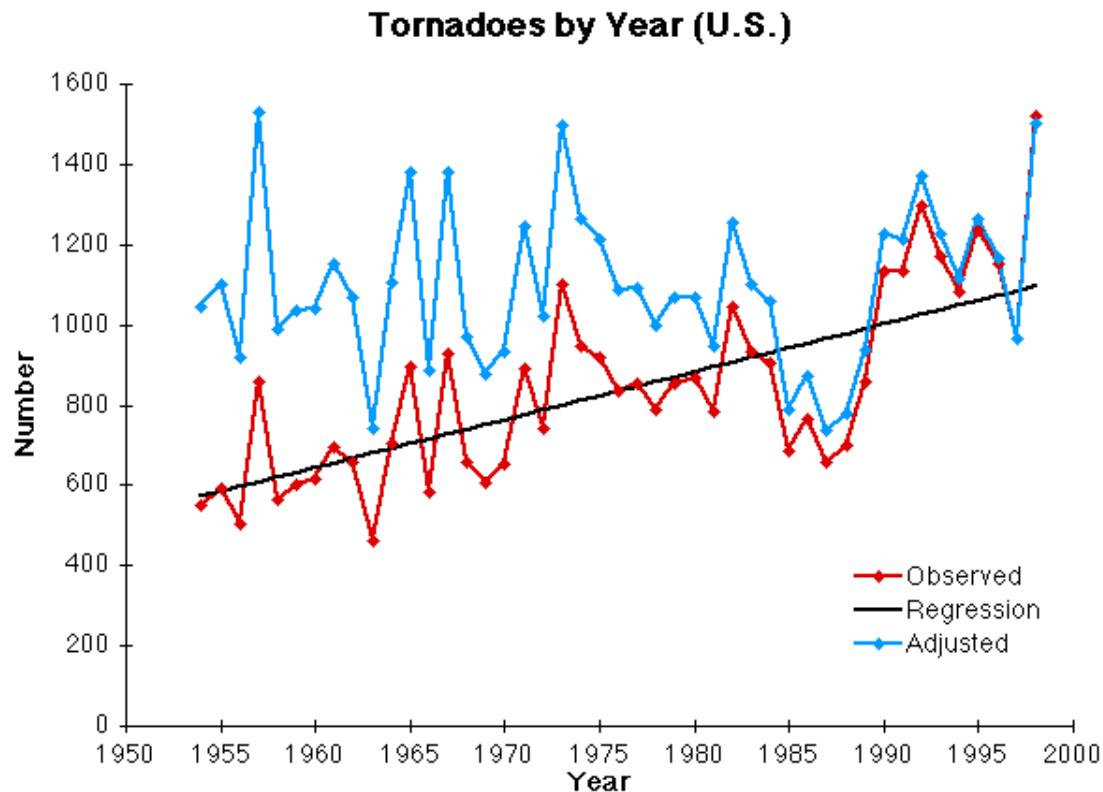
- ▣ What does this mean in terms of amplifying error?

Least Squares Problems

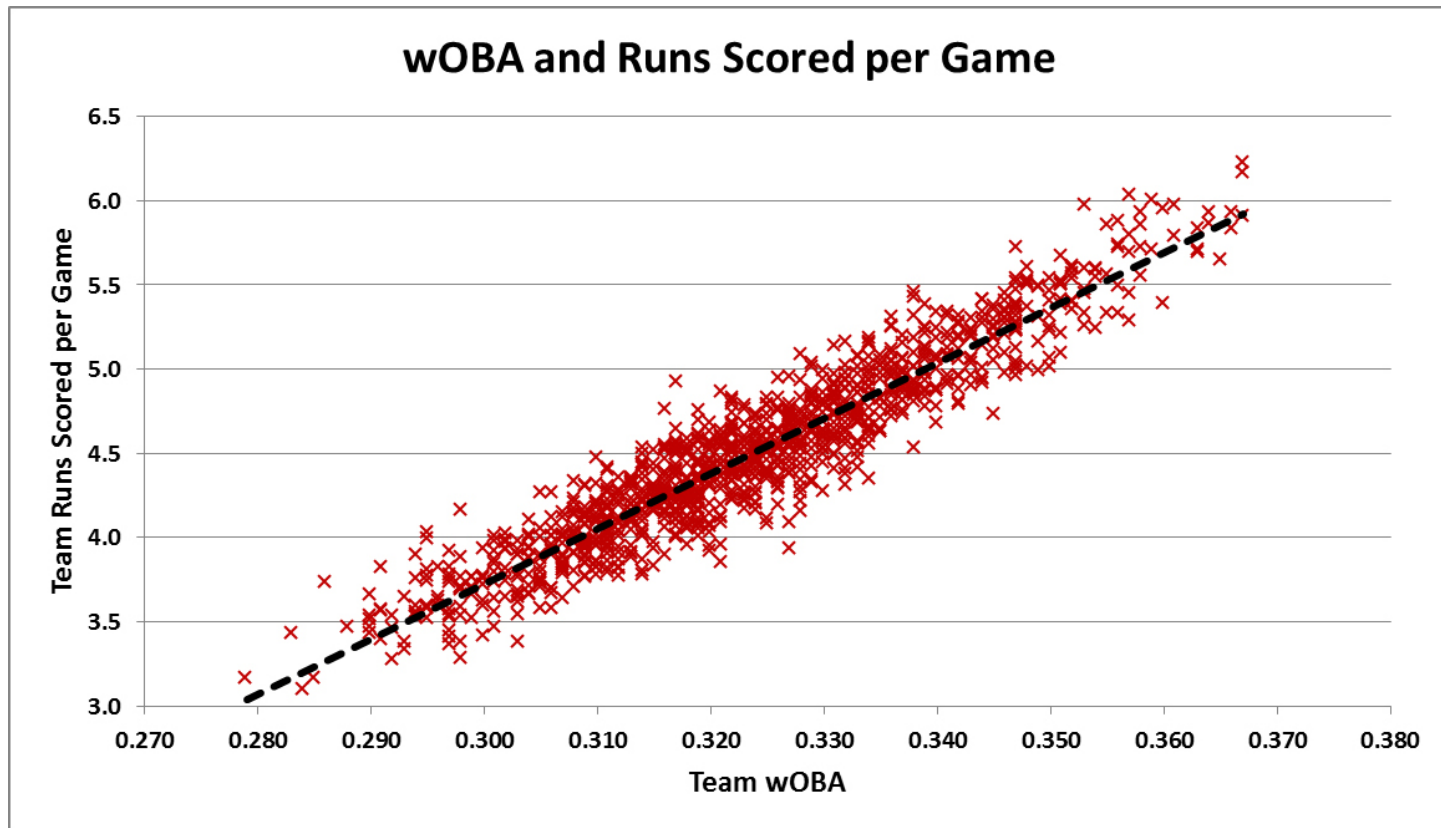
- ▣ Lots of interesting problems lack an exact solution....
- ▣ Fit a line to a set of points....



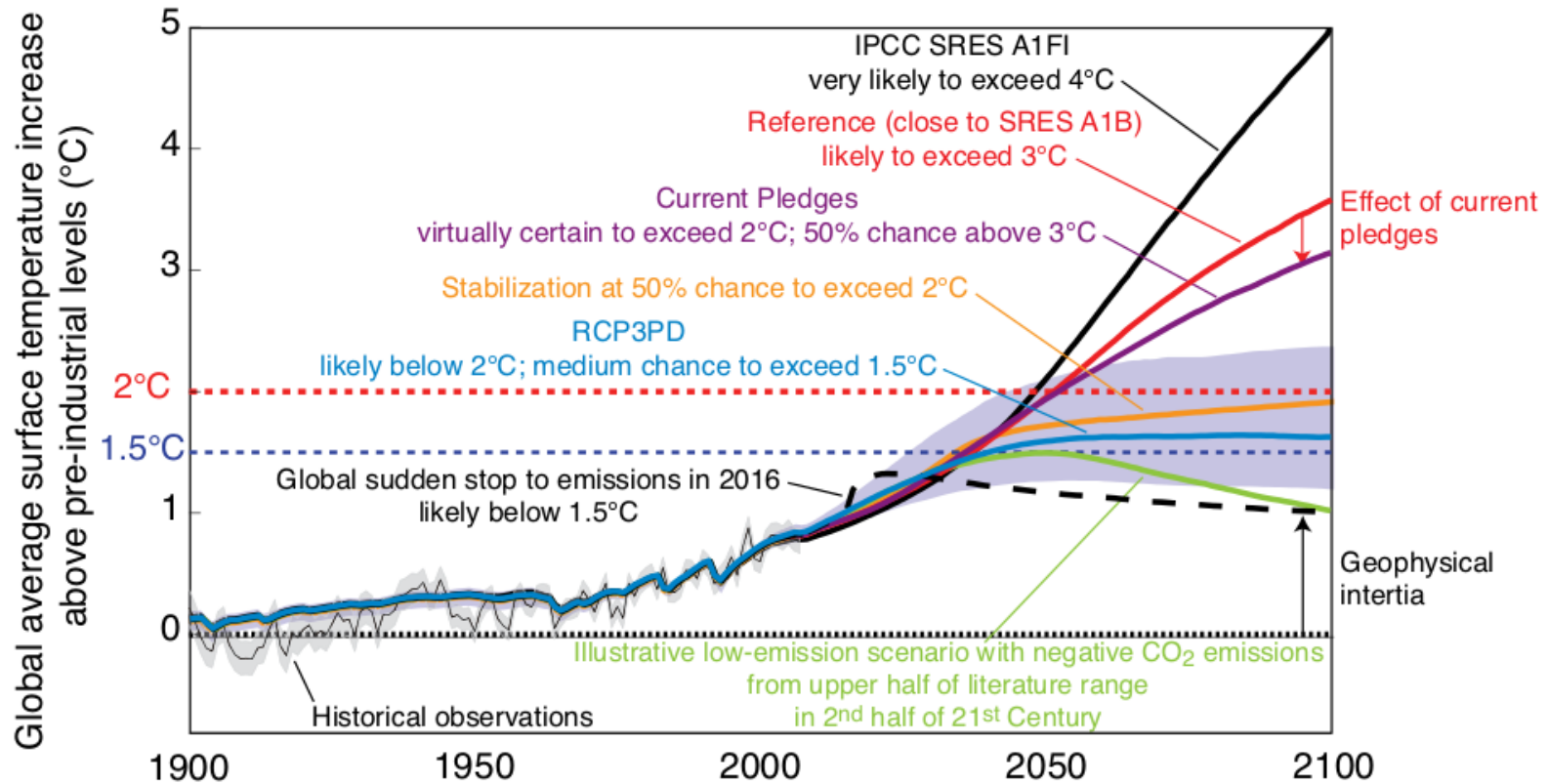
Least Squares Applications



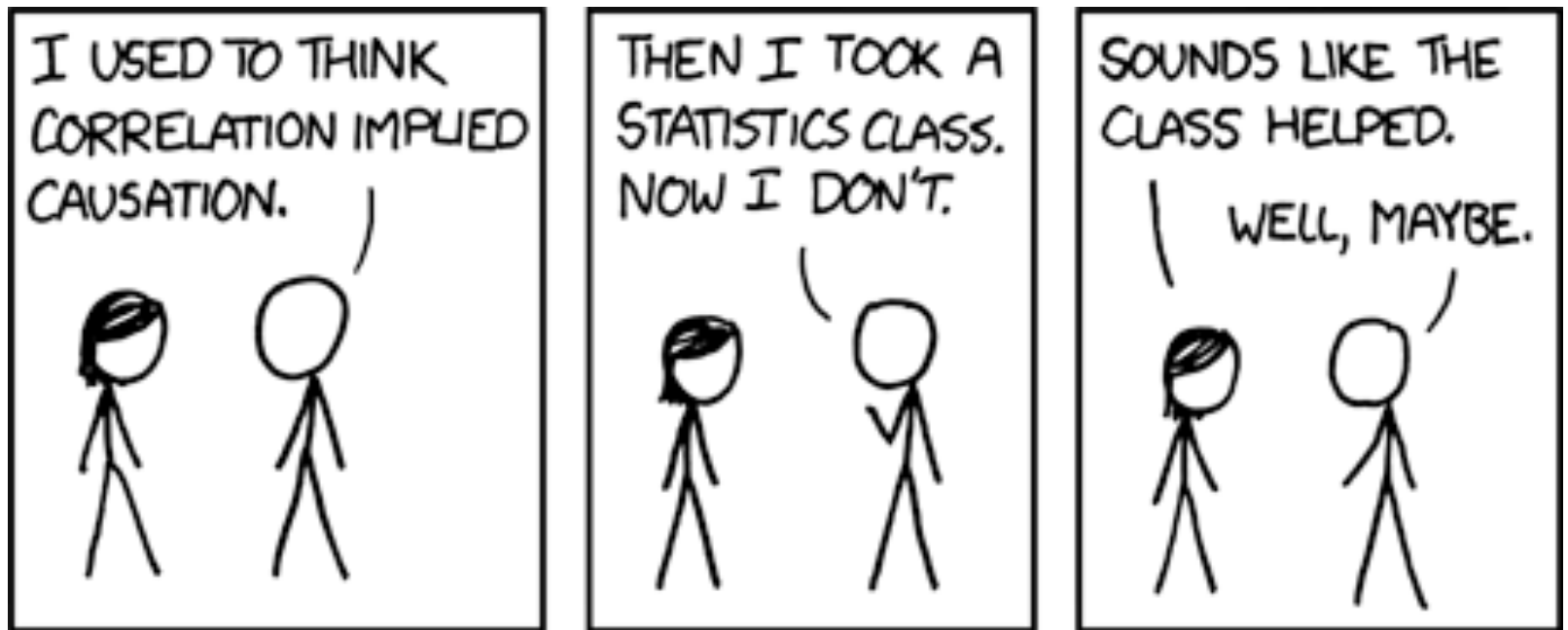
Least Squares Applications



Least Squares Applications



Beware: correlation and causation



Preview: Least Squares as Linear Algebra

Let's fit a line to series of data sampled over times $t_0, t_1, t_2, \dots, t_{m-1}$

The line is given by $f(t) = x_1 t + x_0$

So...how does orthogonality relate to least squares?

- The closest fit to the observed data is an orthogonal projection into the column space of a matrix....
 - You'll understand later....

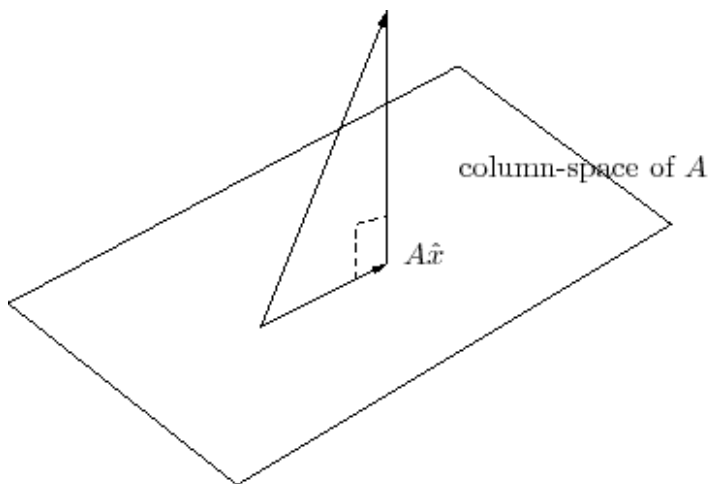


Figure J.1: Geometrical interpretation of orthogonal projection.

Recap: Orthonormal Basis

- A basis is orthonormal if each basis vector:
 - Has unit length
 - Is orthogonal to all other basis vectors.
- Example: $(1,0)$ and $(0,1)$ for 2D Euclidean space
- Can you give another 2D orthonormal basis?

Recap: Orthonormal Basis

For some given vector \vec{x} , how do I find coefficients with respect to an ONB?

$$\vec{x} = \underbrace{(x \cdot b_1)} \vec{b}_1 + \underbrace{(x \cdot b_2)} \vec{b}_2 + \underbrace{(x \cdot b_3)} \vec{b}_3 + \dots + \underbrace{(x \cdot b_n)} \vec{b}_n$$

Much easier than finding coefficients by solving a linear system!

Also much cheaper: $O(n^2)$

Recap: Orthonormal Basis

Can we build a matrix that computes those coefficients for us?

$$Q = \begin{pmatrix} | & & | \\ \vec{b}_1 & \dots & \vec{b}_n \\ | & & | \end{pmatrix} \quad \rightarrow \quad Q^T x = \begin{pmatrix} \vec{b}_1 \cdot \vec{x} \\ \vdots \\ \vec{b}_n \cdot \vec{x} \end{pmatrix}$$

A square matrix whose columns are orthonormal is called orthogonal.



Example

Orthogonal Projection

What if Q contains a few zero columns instead of orthonormal vectors?

$$Q = \begin{array}{|c|c|c|c|} \hline | & & | & \\ \hline \vec{b}_1 & \dots & \vec{b}_k & 0 \\ \hline | & & | & \\ \hline \end{array}$$

↑
orthonormal columns

Define $P := QQ^T$

Compute $P\vec{x}$ for $\vec{x} = \alpha_1\vec{b}_1 + \dots + \alpha_n\vec{b}_n$:

$$Q^T\vec{x} = \begin{pmatrix} \vec{x} \cdot \vec{b}_1 \\ \vdots \\ \vec{x} \cdot \vec{b}_k \\ 0 \\ \vdots \\ 0 \end{pmatrix}$$

Orthogonal Projection

Define $P := QQ^T$

Compute $P\vec{x}$ for $\vec{x} = \alpha_1\vec{b}_1 + \dots + \alpha_n\vec{b}_n$:

$$Q^T\vec{x} = \begin{pmatrix} \vec{x} \cdot \vec{b}_1 \\ \vdots \\ \vec{x} \cdot \vec{b}_k \\ 0 \\ \vdots \\ 0 \end{pmatrix}$$

$$Q(Q^T\vec{x}) = \underbrace{(\vec{x} \cdot \vec{b}_1)\vec{b}_1 + \dots + (\vec{x} \cdot \vec{b}_k)\vec{b}_k}_{\substack{\text{x projected onto} \\ \vec{b}_1, \dots, \vec{b}_k}} + \underbrace{0 \cdot \vec{b}_{k+1} + \dots + 0 \cdot \vec{b}_n}_{\vec{0}}$$

Example

Gram-Schmidt Orthogonalization

- Given linearly independent a_1 and a_2
- Find q_1 and q_2 that are orthonormal and span same space

Classical Gram-Schmidt

- ▣ We can orthogonalize any number of vectors...

```
for k in range(A.shape[1]):  
    avec = A[:, k]  
    q = avec  
    for j in range(k):  
        q = q - np.dot(avec, Q[:,j])*Q[:,j]  
  
    Q[:, k] = q/la.norm(q)
```

Problems

- Rounding error can destroy orthogonality in the q_k vectors
- Also we need to store A , Q and R separately
 - problematic for large systems

Modified Gram-Schmidt

```
for k in range(A.shape[1]):  
    q = A[:, k]  
    for j in range(k):  
        q = q - np.dot(q, Q[:,j])*Q[:,j]  
  
    Q[:, k] = q/la.norm(q)
```