

CS 357: Numerical Methods

Singular Value Decomposition
Rank-K Approximations
Total Least Squares

Eric Shaffer

Computing the SVD

$$A = U \Sigma V^T$$

① Find v

$$A^T A v_i = \lambda_i v_i$$

$$V = \begin{bmatrix} | & & | \\ v_1 & \dots & v_n \\ | & & | \end{bmatrix}$$

A $m \times n$

V $n \times n$

② Form Σ

$$\begin{bmatrix} \sqrt{\lambda_1} & & 0 \\ & \dots & \\ 0 & & \sqrt{\lambda_n} \end{bmatrix}$$

Σ $m \times n$

Computing the SVD

$$A = U \Sigma V^T$$

$$AV = U \Sigma$$

if A $n \times n$

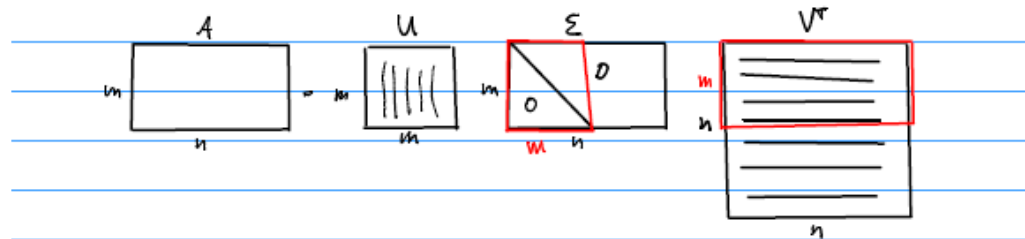
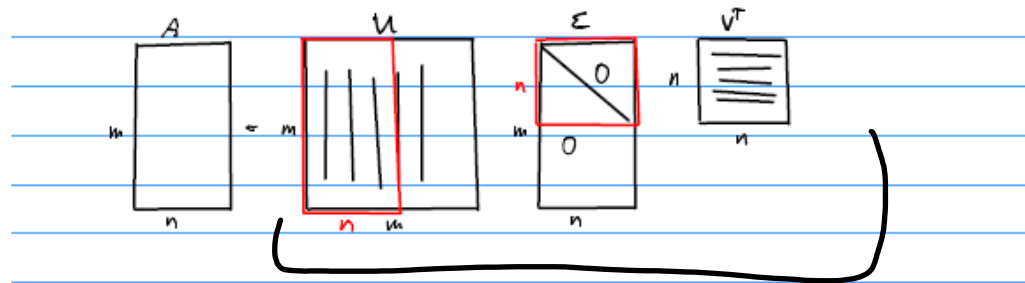
$$AV \Sigma^+ = U \begin{bmatrix} 1 & \dots & 1 \end{bmatrix}$$

Pseudoinverse of Σ

$$\Sigma = \begin{bmatrix} & n \\ m & \end{bmatrix} \quad \Sigma^+ = \begin{bmatrix} & \\ & \end{bmatrix}$$

$$\Sigma^+ = \begin{bmatrix} 1/\sqrt{\lambda_1} & \dots & 1/\sqrt{\lambda_n} \end{bmatrix}$$

Reduced Form of the SVD



"Full" version shown in black

"Reduced" version shown in red

Rewriting the SVD

$$A = U \Sigma V^T = \begin{pmatrix} | & & | \\ u_1 & \dots & u_n \\ | & & | \end{pmatrix} \begin{pmatrix} \sigma_1 & & \\ & \dots & \\ & & \sigma_n \end{pmatrix} \begin{pmatrix} -v_1- \\ \vdots \\ -v_n- \end{pmatrix}$$

$$A = \sum \sigma_i \underbrace{u_i v_i^T}_{\text{outer product}}$$

2×1 1×2

$$\begin{pmatrix} 2 \\ 4 \end{pmatrix} \begin{pmatrix} 1 & 3 \end{pmatrix} = \begin{pmatrix} 2 & 6 \\ 4 & 12 \end{pmatrix}$$

Rank-K Approximations

X is a set of 2D points

$$X = \begin{pmatrix} | & & | \\ x_1 & \dots & x_n \\ | & & | \end{pmatrix}$$

n points

x_i is the i th point

$$X \overset{2 \times n}{=} U \Sigma V^T$$

\downarrow 2×2 \downarrow 2×2 \rightarrow $2 \times n$

u_1 first col of u

σ_1 top σ_i in Σ

v_1^T first row of v^T

For Rank-1 approx

$$X \approx u_1 \sigma_1 v_1^T = X_1$$

Rank-K Approximations

Frobenius Norm

$$\|X\|_F = \sqrt{x_{11}^2 + x_{12}^2 + \dots + x_{mn}^2}$$

$\|X - B\|_F^2$ is minimized by $B = X_1$,
where B is rank 1 matrix

$$\|X - X_1\|_F^2 = \sum \|x_{.j} - \underbrace{u_1 \sigma_1 v_j}_{\text{scalar multiple of vector } u_1}\|_2^2$$

Rank-K Approximations

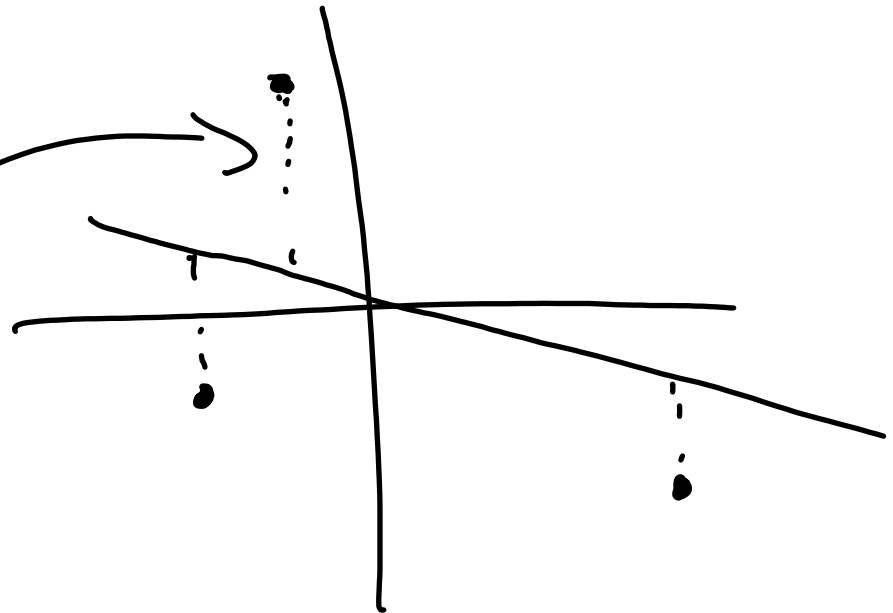
v_1 from V is eigenvector of $A^T A$
 u_1 from U is principal e.vec of $A A^T$

Rank-2 approximation finds
2 vectors spanning a plane
having minimal distance to
data points

Total Least Squares

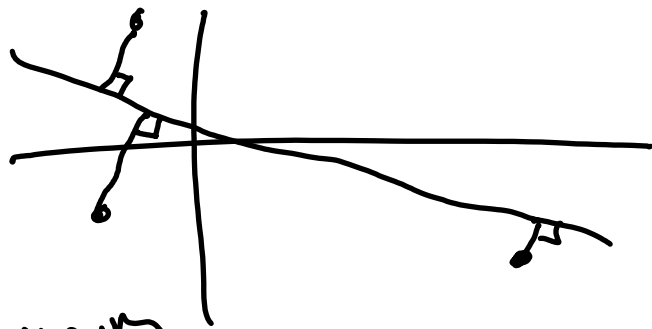
$$(t_i, y_i) = (-2, -1)$$
$$(-1, 3)$$
$$(3, -2)$$

Linear
Least
Squares
minimizes
vertical
distances



Total Least Squares

Imagine points (t_i, y_i) have
error in both t_i and y_i



Minimize dist
perp. to line

"Ordinary
least
squares"

$$Ax \approx b$$

we want to find \tilde{x}

$$A\tilde{x} = y \text{ and}$$

$\|b - y\|_2$ is minimal
and $y \in \text{span}(A)$

Total Least Squares

Ordinary least squares $b \approx y$
 \rightarrow RHS varies

$$Ax \approx b$$

$$\hat{A}x = y$$

For total least squares
A varies as well

$$[Ab] = U \Sigma V^T \rightarrow m \times (n+1)$$

find $\underbrace{[\hat{A}y]}$ approximates $[Ab]$
 $\hookrightarrow y \in \text{span } \hat{A}$

Total Least Squares

Use rank n approx. of $[A \ b]$

$$\underbrace{[\hat{A} \ y]}_{\text{rank } n} \begin{bmatrix} x \\ -1 \end{bmatrix} = 0$$

$$\boxed{\hat{A}x = y}$$

$\rightarrow [x^T \ -1]^T$ is in null space $[\hat{A} \ y]$

$\rightarrow [x^T \ -1]$ proportional to v_{n+1}

$$X \approx \frac{1}{v_{n+1, n+1}} \begin{bmatrix} v_{1, n+1} \\ \vdots \\ v_{n+1, n+1} \end{bmatrix}$$

$$[A \ b] = U \Sigma V^T$$

$v_{n+1} \rightarrow$ last col V