

# CS 357: Numerical Methods

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## Principal Component Analysis Interpolation

Eric Shaffer

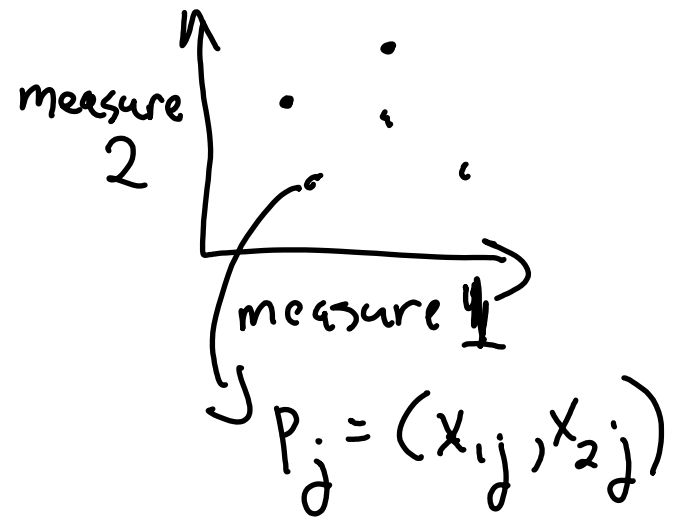
# Principal Component Analysis Revisited

Consider  $n$  trials  
 Each trial produces  
 an  $m$  dim. point

$$X = \left( \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right) \downarrow \begin{array}{l} i \text{ measure} \\ \vdots \\ \vdots \\ \vdots \end{array}$$

$j \rightarrow \text{trial}$

$$\left( \begin{array}{c|ccc} & P_i & & \\ \hline & x_{11} & x_{12} & \dots \\ & x_{21} & x_{22} & \dots \end{array} \right)$$



# Principal Component Analysis Revisited

① Compute estimate of mean

$$u_i = \frac{1}{n} \sum_j x_{ij}$$

row-wise average

②  $y_{ij} = x_{ij} - u_i = Y$

③  $C = \frac{1}{n-1} (Y Y^T)$

# Principal Component Analysis Revisited

Principal Component  
are columns of  $U$   
in  $\left(\frac{1}{\sqrt{n-1}}\right) Y = U \Sigma V^T$

# Interpolation

- Suppose we have the following discrete data

t	-2	0	1
y	-27	-1	0

- Common things we wish to do include:
  - Draw a smooth curve through the data points
  - Infer values between the points
  - Predict future values
  - Approximate the function that generated the values
    - In way that allows us to find a derivative or integral
    - Compute new values of the function quickly

# Interpolation

- Interpolation is the process of fitting a function to data such that the function matches the given data values **exactly**.
- Such a function is called an **interpolant**.
- Consider computing a line  $y = x_1 + x_2 t$  to the data points  $(t_1, y_1)$  and  $(t_2, y_2)$
- What does the line give us that the points don't?

# What form should an interpolant have?

- Depends on a number of factors
  - How easy should it be to evaluate at other points?
  - Does the application require certain behavior?
    - Periodicity
    - Convexity
    - Monotonicity
- Common choices include
  - Polynomials and piecewise polynomials
  - Trigonometric functions
  - Exponential functions

# Existence and Uniqueness

- Existence and uniqueness are determined by
  - The number of data points
  - The number of parameters in the interpolant

- Too few parameters  $\rightarrow$  interpolant does not exist

Example?  $f(x) = x_1 + x_2$  to 1,000,000

- Too many parameters  $\rightarrow$  interpolant is not unique

Example?





# Basis Functions

Given a set of data points an interpolant is chosen from a set of basis functions  $\phi_1(t), \dots, \phi_n(t)$

that span a space of functions.

The interpolant is expressed as a linear combination of the basis functions

$$f(t_i) = \sum_{j=1}^n x_j \phi_j(t_i) = y_i$$

weight  $\leftarrow$   $x_j$   $\phi_j(t_i)$  basis function  $y_i$

# Determining the interpolant parameters

- Requiring that  $f$  interpolate  $(t_i, y_i)$  means

$$f(t_i) = \sum_{j=1}^n x_j \phi_j(t_i) = y_i$$

- This is a system of linear equations

$$A x = y$$

$$a_{ij} = \phi_j(t_i)$$

$y_i$  are known

$x_i$  are unknown coeffs.

# Existence and Uniqueness

$$Ax = y$$

- If the number of parameters = number of data points

- And what else?

*A is nonsingular*

We have a unique interpolant

- If the number of parameters  $>$  number of points

- Interpolant is not unique

- Why might that be useful?

# Choice of basis functions

- The choice of basis functions affects
  - The conditioning of  $A$
  - The amount of work to solve the system
  - Anything else?

Computational cost of  
evaluating the  
interpolant

# The monomial basis

$$\phi_j(t) = t^{j-1} \quad \text{for } j=1, \dots, n$$

for  $n$  data points

$$p_{n-1}(t) = x_1 + x_2 t + x_3 t^2 + \dots + x_n t^{n-1}$$

polynomial of degree  $n-1$   
have  $n$  parameters

# The Vandermonde matrix

$$Ax = \begin{bmatrix} 1 & t_1 & t_1^2 & \dots & t_1^{n-1} \\ 1 & t_2 & t_2^2 & \dots & t_2^{n-1} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & t_n & t_n^2 & \dots & t_n^{n-1} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix}$$

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if  $Az = 0 \rightarrow$  poly w/ coeffs given by  $z$   
has  $n$  zeros  $\rightarrow z = 0$

# Example

$$\begin{matrix} (-2, -27) & (0, -1) & (1, 0) \\ \text{fit } P(t) = & x_1 + x_2 t + x_3 t^2 \end{matrix}$$

$$A x = \begin{bmatrix} 1 & -2 & 4 \\ 1 & 0 & 0 \\ 1 & 1 & 1 \end{bmatrix} x = \begin{bmatrix} -27 \\ -1 \\ 0 \end{bmatrix}$$

Solve w/ GF

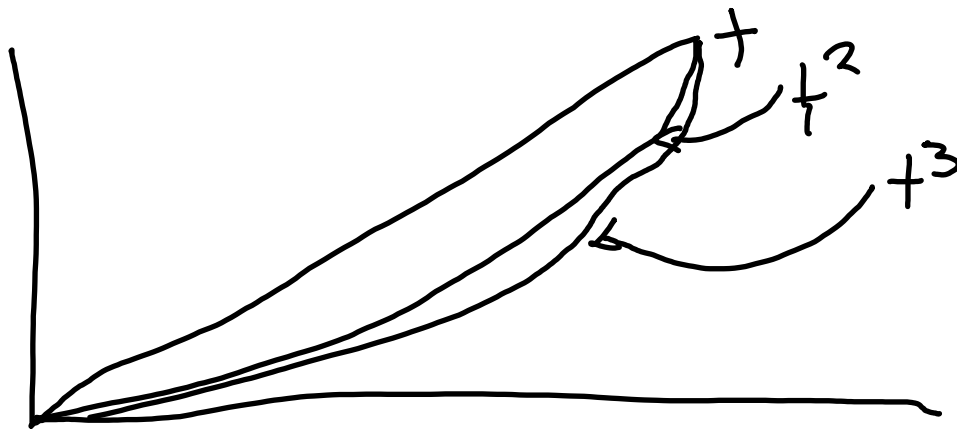
$$x = \begin{bmatrix} -1 \\ 5 \\ -4 \end{bmatrix}$$

# Example



# Complexity and Conditioning

- What is the complexity of solving the system?  $O(n^3)$
- The Vandermonde matrix is often ill-conditioned



as  $n$  gets larger

columns get  
closer to  
linearly dependent

# Evaluating a polynomial

- What is cost of evaluating polynomial of degree  $n-1$ ?

$$P_{n-1} = x_1 + x_2 + \dots + x_n^{n-1}$$

$O(n)$  additions

$$\text{mults} = 1 + 2 + \dots + n-1$$
$$O(n^2)$$

# Horner's Method

$$p_{n-1} = x_1 + t(x_2 + t(x_3 + t(\dots(x_{n-1} + tx_n))))$$

$O(n)$  adds  
 $O(n)$  mults

# Example

$$1 - 4t + 5t^2 - 2t^3 + 3t^4$$
$$= 1 + t(-4 + t(5 + t(-2 + 3t)))$$