

Exam on Wed.

5-8

9.2 Numerical Methods (pt. I)

$$y'(t) = f(y(t))$$

$$y(t_0) = y_0$$

$$h : \quad \begin{array}{ccc} t_1 = t_0 + h & , & t_2 = t_0 + 2h. \dots \\ \uparrow & & \uparrow \\ y_1 & & y_2 \dots \end{array}$$

"Integral equation"

$$y(t) = y_0 + \int_{t_0}^t f(y(\tau)) d\tau$$

Idea: use trapezoidal rule:

$$y_{k+1} = y_k + f(y_k) \cdot \frac{h}{2} + f(y_{k+1}) \cdot \frac{h}{2}$$

??

?

Have to solve
an eqn

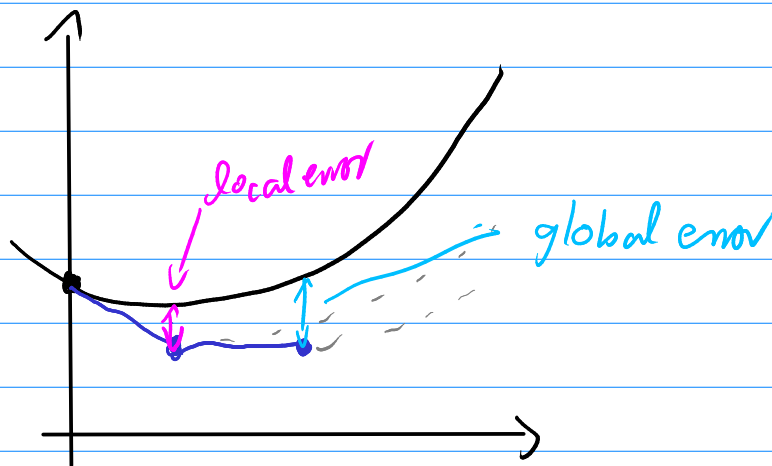
("backward Euler")

Idea 2: use left-handed rectangle rule

$$y_{k+1} = y_k + h \cdot f(y_k)$$

("Euler / forward Euler")

9.3 Accuracy and Stability



local error: $l_k = y_{k+1} - u_k(t_{k+1})$ $u_k(t)$ solves ODE
with IC: $u(t_k) = y_k$

global error: $y_k - y(t_k)$

global error $\neq \sum$ (local errors)
>

Time integrator is of order p i.e. $l_k = O(h^{p+1})$

\sum local errors over unit-length

$$\frac{1}{h} \cdot O(h^{p+1}) = O(h^p)$$

↑
#steps in $(0,1)$

Stability

Instability:

- could be ODE instability
- could be the method

For Euler: $y'(t) = \lambda y(t)$

$$\begin{aligned}y_{k+1} &= y_k + h \lambda y_k \\ &= y_k (1 + h \lambda)\end{aligned}$$

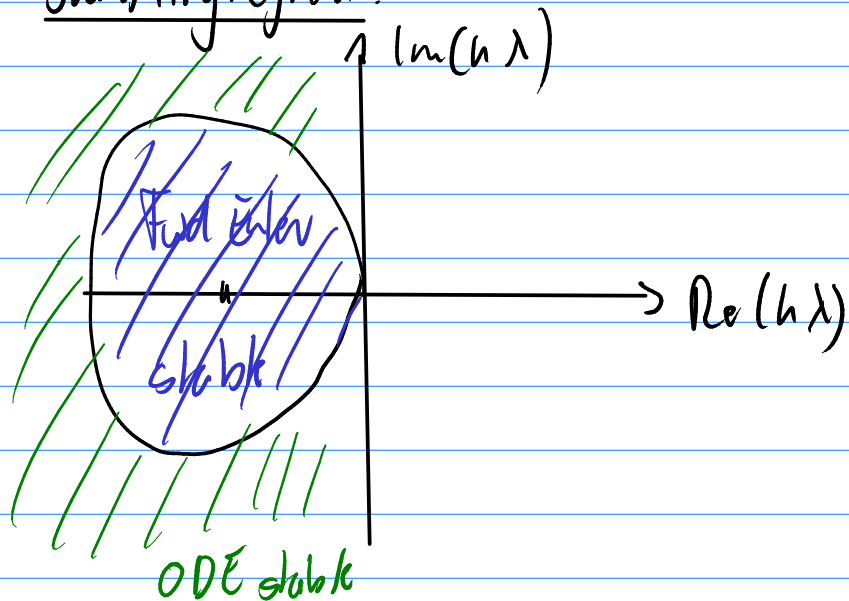
$$|y_{k+1}| = |y_k| |1 + h \lambda| = |y_0| |1 + h \lambda|^{k+1}$$

$(h\lambda - (-1))$ stable $\Leftrightarrow |1 + h\lambda| \leq 1$

growth factor

radius

"Stability region":



Stability in the nonlinear case

Fw Euler: (A) $y_{k+1} = y_k + h f(y_k)$

Taylor: (B) $y(t_{k+1}) = y(t_k) + h f(y(t_k)) + O(h^2)$

(A)-(B) $e_{k+1} = y_{k+1} - y(t_{k+1}) = \underbrace{y_k - y(t_k)}_{e_k} + \underbrace{h(f(y_k) - f(y(t_k)))}_{\text{propagated error}} + \underbrace{O(h^2)}_{\text{local error}}$