

# 257 Summary

TODO:

- How did we deduce TVD for the PDE?
- Lax's entropy condition:  $<$  or  $\leq$ ?
- Strange second integral condition in derivation of Godunov.
- Why the meshing restriction for FD?

## 1 Miscellanea

- An interpolation polynomial is monotone in a jump cell.  
Example: Degree-five polynomial, six points, degree-four derivative, four derivative zeros in each of the boundary cells  $\Rightarrow$  none in the center jump cell.

## 2 Theory

- *Conservation Law*:  $u_t + f(u)_x = 0$ . Initial condition  $u_0$ .
- *Integral form*:

$$\frac{d}{dt} \int_a^b u(x, t) dx = f(u(b, t)) - f(u(a, t)). \quad (1)$$

- *Characteristic*: Defined by

$$\frac{d}{dt} u(x(t), t) = u_x x' + u_t \stackrel{!}{=} 0,$$

setting  $x' = f'$ . May cross.

- *Weak solution*:
  - (1) for almost all  $(a, b)$
  - For any  $\varphi \in C_0^1(\mathbb{R}^2)$ ,  $t > 0$

$$-\int_0^t \int_{-\infty}^{\infty} u \varphi_t + f(u) \varphi_x dx dt - \int_{-\infty}^{\infty} u_0(x) \varphi(x, 0) dx = 0.$$

Both definitions equivalent.

- *Rankine-Hugoniot condition*: Curve parameterized by  $(x(t), t)$  separates two smooth regions.

$$s = x'(t) = \frac{[[f]]}{[[u]]}$$

Proof: Split (1) at  $x(t)$ , carry out time derivative, observe Leibniz rule, apply conservation law.

- *Riemann problem*: Conservation law with single-jump (otherwise constant) IC.  
Rarefaction  $(-1, x/t, 1)$  is a weak solution, jump is also weak solution  $\Rightarrow$  non-uniqueness.  
If  $f$  is convex, the general solution

$$u(x, t) = \begin{cases} \begin{cases} u_l & x < st, \\ u_r & x > st, \end{cases} & u_l > u_r, \\ \begin{cases} u_l & x < f'(u_l)t, \\ (f')^{-1}(x/t) & \text{otherwise,} \\ u_r & x > f'(u_r)t, \end{cases} & u_l < u_r. \end{cases}$$

- *Vanishing viscosity method*: add  $u_{xx}^\varepsilon$  to the RHS of the conservation law, letting  $\varepsilon \rightarrow 0$ .
- *Entropy function*:  $U$  convex ( $U'' \geq 0$ ).
- *Entropy flux*:  $F'(u) = U'(u)f'(u)$ .
- *Entropy condition*:  $(U, F)$  an entropy-entropy flux pair. Then  $u$  is an entropy solution iff

$$U(u)_t + F(u)_x \geq 0$$

weakly.

Proof: Multiply c.law by  $U'(u^\varepsilon)$ , gather derivatives. On RHS, write

$$U'(u^\varepsilon)u_{xx}^\varepsilon = (U'(u^\varepsilon)u_x^\varepsilon)_x - U''(u^\varepsilon)(u_x^\varepsilon)^2 \leq (U'(u^\varepsilon)u_x^\varepsilon)_x.$$

Then multiply by smooth  $\varphi \geq 0$  and integrate by parts twice. Pass to limit by DCT, RHS vanishes because  $u^\varepsilon$  is bounded–maximum principle.

- The conservation law is
  - *Genuinely nonlinear*:  $f''(u) \neq 0$  uniformly,
  - *Convex*:  $f''(u) > 0$  uniformly,
  - *Concave*:  $f''(u) < 0$  uniformly.
- *Other Entropy conditions*:
  - *Motivation*:  $x'(t)[U] \leq [F]$  by applying a Rankine-Hugoniot type argument to  $U(u)_t + F(u)_x \geq 0$ .
  - *Oleinik entropy condition*: For all  $u \in [u^-, u^+]$ :

$$\frac{f(u) - f(u^-)}{u - u^-} \geq s \geq \frac{f(u) - f(u^+)}{u - u^+},$$

where  $s$  is the shock speed from Rankine-Hugoniot.

- *Lax entropy condition*:

$$f'(u^-) \geq s \geq f'(u^+).$$

Not sufficient for uniqueness, but necessary.

Sufficient if  $f'(u) \geq 0$  uniformly. Simpler if  $f'(u) > 0$ :

$$f'(u^-) \geq f'(u^+).$$

Since  $f'$  is  $\nearrow$ , we can only jump down.

*Meaning*: Characteristics only go *into* shocks, never out of them.

- *$L^1$  contraction*: For  $u_t^\varepsilon + f(u^\varepsilon)_x = \varepsilon u_{xx}^\varepsilon$  with  $u^\varepsilon(0, t) = u_0(x)$ , we have

$$\|u^\varepsilon(\cdot, t) - v^\varepsilon(\cdot, t)\|_{L^1} \leq \|u^0 - v^0\|_{L^1},$$

where  $v^\varepsilon$  solves the same PDE with IC  $v^0$ .

Proof: Chop up

$$\frac{d}{dt} \int_{-\infty}^{\infty} |u^\varepsilon - v^\varepsilon|$$

at the sign changes. Put in  $s_j$  as a sign function on each interval. Use Leibniz's rule, then the c.law, which can be integrated out to zero, leaving some  $u_x$  terms, which can be deduced to have the right sign.

- *Total Variation*:

$$\text{TV}(u) := \sup_h \int \frac{|u(x+h) - u(x)|}{h} dx$$

*TVD*:  $\text{TV}(u(\cdot, t)) \leq \text{TV}(u^0)$ . **XXX WHY?**

### 3 Numerics

- *Bad example:* Discretize  $u_t = u u_x$  255-style, and get a monstrosity that leaves a 1-0 shock just where it is.

- *Conservative scheme:*

$$u_j^{n+1} = u_j^n - \frac{\Delta t}{\Delta x} [\hat{f}_{j+1/2} - \hat{f}_{j-1/2}],$$

with

- $\hat{f}$  consistent, i.e.  $\hat{f}(u, \dots, u) = f(u)$ ,
- $\hat{f}$  locally Lipschitz.

- *Summation by parts:*

$$\sum_{j=j_1}^{j_2} a_j (b_j - b_{j-1}) = - \sum_{j=j_1}^{j_2} (a_{j+1} - a_j) b_j - a_{j_1} b_{j_1-1} + a_{j_2} b_{j_2}.$$

- *Lax-Wendroff:* If  $\{u_j^n\}$  converges ( $\Delta t, \Delta x \rightarrow 0$ ) boundedly a.e. to a function  $u \Rightarrow u$  a weak solution. Proof: Summation by parts, DCT, Conservativity.

- *Schemes:*

- *Godunov:* Exploit finite propagation speed, solve Riemann problem on each cell, demanding that

$$\int_{I_j} \int_t (u_t + f(u)_x) dx dt = 0.$$

To get  $\hat{f}_{j+1/2}^n$ , use the exact Riemann solution at  $x_{j+1/2}$ .

$$\hat{f}_{j+1/2} = \begin{cases} \min_{[u_j, u_{j+1}]} f(u) & u_j < u_{j+1}, \\ \max_{[u_j, u_{j+1}]} f(u) & u_j \geq u_{j+1}. \end{cases}$$

- *Lax-Friedrichs:*

$$\hat{f}_{j+1/2} = \frac{1}{2} [f(u_{j+1}) + f(u_j) - \alpha_{j+1/2} \Delta_+ u_j]$$

- *local Lax-Friedrichs:*  $\alpha_{j+1/2} = \max_{[u_j, u_{j+1}]} |f'(u)|$ ,
- *global Lax-Friedrichs:*  $\alpha_{j+1/2} = \max_u |f'(u)|$ .

- *Roe:*

$$\hat{f}_{j+1/2} = \begin{cases} f(u_j) & a_{j+1/2} \geq 0 \\ f(u_{j+1}) & a_{j+1/2} < 0 \end{cases}, \quad \text{where } a_{j+1/2} = \frac{\Delta_+ f(u_j)}{\Delta_+ u_j}.$$

- *Engquist-Osher:*

$$\begin{aligned} \hat{f}_{j+1/2} &= f^+(u_j) - f^-(u_{j+1}), \\ f^+(u) &= \int_0^u f'(u) \vee 0 du + f(0), \\ f^-(u) &= \int_0^u f'(u) \wedge 0 du. \end{aligned}$$

- *Lax-Wendroff:*

- Taylor-expand  $u^{n+1}$  in  $t$ .
- Replace time derivatives with 2nd-order centered differences to desired order.

$$\hat{f}_{j+1/2} = \frac{1}{2} [f(u_j) + f(u_{j+1}) - \lambda f'(u_{j+1/2})(f(u_{j+1}) - f(u_j))],$$

where

$$u_{j+1/2} = \frac{u_{j+1} + u_j}{2}, \quad \lambda = \frac{\Delta t}{\Delta x}.$$

- *McCormack*: Predictor-corrector-style

$$\begin{aligned} u_j^{n+1/2} &= u_j^n - \lambda(f(u_j^n) - f(u_{j-1}^n)), \\ u_j^{n+1} &= \frac{1}{2} \left[ u_j^n + u_j^{n+1/2} + \lambda \left[ f(u_{j+1}^{n+1/2}) - f(u_j^{n+1/2}) \right] \right]. \end{aligned}$$

- *Monotone schemes*: Write  $u_j^{n+1} = G(u_{j-p-1}, \dots, u_{j+q})$ . Monotone iff  $G(\uparrow, \uparrow, \uparrow)$ .
  - *For three-point schemes*:  $G(u_{j-1}, u_j, u_{j+1}) = u_j - \lambda[\hat{f}(u_{j+1}, u_j) - \hat{f}(u_{j-1}, u_j)] \Rightarrow G(\uparrow, ?, \uparrow)$ .  
 $\partial_{u_j} G = 1 - \lambda(\hat{f}_1 - \hat{f}_2) \geq 0!$
  - L-F is monotone.

Properties:

- $u_j \leq v_j$  for all  $j \Rightarrow G(u_j) \leq G(v_j)$   
 Proof: by definition.
- Local maximum principle

$$\min_{i \in \text{stencil}_j} u_i \leq G(u_j) \leq \max_{i \in \text{stencil}_j} u_i$$

Proof: Define  $w$  to be  $\min_{\text{stencil}}$  on the stencil and  $u$  otherwise. Then

$$\min_{\text{stencil}} = G(w) \leq G(u).$$

- *Crandall/Tartar Lemma/ $L^1$  contraction*:  $\|G(u) - G(v)\|_{L^1} \leq \|u - v\|_{L^1}$   
 Proof: Let  $w := u \vee v$ . Then  $G(u), G(v) \leq G(w)$  and  $G(w) - G(v) \geq (G(u) - G(v))^+$ . Then

$$\sum (G(u) - G(v))^+ \leq \sum [G(w) - G(v)]^{\text{conservative}} = \sum (w - v) = \sum (u - v)^+.$$

- *TVD*. Take  $v_j = u_{j+1}$  in  $L^1$  contraction.
- *Cell entropy inequality*: Let  $U(u) = |u - c|$  and  $\hat{F} = \hat{f}(c \vee u) - \hat{f}(c \wedge u)$ .

$$\frac{U(u_j^{n+1}) - U(u_j^n)}{\Delta t} - \frac{\hat{F}_{j+1/2} - \hat{F}_{j-1/2}}{\Delta x} \leq 0$$

Proof: Show

$$G(c \vee u_j) - G(c \wedge u_j) = |u_j^n - c| - \lambda(\hat{F}_{j+1/2} - \hat{F}_{j-1/2})$$

by starting with the LHS. Next,  $c \vee u_j^{n+1} \leq G(c \vee u^n)_j$  and so

$$U(u^{n+1})_j = |u_j^{n+1} - c| \leq G(c \vee u^n)_j - G(c \wedge u^n)_j.$$

- *Godunov's Theorem*: Monotone schemes are at most first-order accurate.  
 Proof: The scheme is second-order accurate for an equation with dissipation, so it can't also be second-order accurate for the original c.law.
- *TVD scheme*.
- *Monotonicity-preserving scheme*:

$$u_j^n \geq u_{j+1}^n \forall j \quad \Rightarrow \quad u_j^{n+1} \geq u_{j+1}^{n+1} \forall j.$$

- *TVD  $\Rightarrow$  monotonicity-preserving*.  
 Proof: Suppose it isn't. Then you can make  $u$  constant outside the relevant stencils. Reversal of order of the two values implies non-TVD.
- *Linear scheme*: Linear if applied to a linear PDE.  
 Also "positive" because Monotone  $\Leftrightarrow$  positive coefficients.  
 Can be written

$$u_j^{n+1} = \sum_{l=-k}^k c_l(\lambda) u_{j-l}^n.$$

- *Linear, monotonicity-preserving*  $\Rightarrow$  *monotone*.  
Proof: Consider first differences of a Heaviside jump  $\Rightarrow$  all coefficients positive.
- *Linear, monotone (TVD)*  $\Rightarrow$  *at most first order*.  
Proof: Plug in constant, linear term, quadratic term to obtain

$$\begin{aligned} 1 &= \sum c_l, \\ \lambda &= \sum l c_l, \\ \lambda^2 &= \sum l^2 c_l. \end{aligned}$$

Then  $\mathbf{a} := (l\sqrt{c_l})$ ,  $\mathbf{b} := (\sqrt{c_l})$  and Cauchy-Schwarz (equality iff  $\mathbf{a} = \alpha\mathbf{b}$ ).

### 3.1 Higher Order TVD Schemes

Assume  $f'(u) \geq 0$  (wind from the left) for the moment.

- *General Finite Volume Framework:*

$$\frac{d}{dt} \int_{x_{j-1/2}}^{x_{j+1/2}} u dx + f(u(x_{j+1/2})) - f(u(x_{j-1/2})) = 0,$$

then

$$\bar{u} := \frac{1}{\Delta x} \int_{x_{j-1/2}}^{x_{j+1/2}} u dx,$$

so

$$\frac{d}{dt} \bar{u}_j = \frac{1}{\Delta x_j} [\hat{f}_{j+1/2} - \hat{f}_{j-1/2}]$$

with

$$\hat{f}_{j\pm 1/2} \approx f(u(x_{j\pm 1/2})).$$

- *Reconstruction:*

$$\begin{aligned} u_{j+1/2}^{(\text{central})} &= \frac{1}{2}(\bar{u}_j + \bar{u}_{j+1}), \\ u_{j+1/2}^{(\text{upwind})} &= \frac{1}{2} \left( 3\bar{u}_j - \frac{1}{2}\bar{u}_{j-1} \right). \end{aligned}$$

Goal is to compute polynomial such that  $\frac{1}{\Delta x} \int_{I_j} p(x) = \bar{u}_j$  for some  $js$ . Then evaluate at  $x_{j+1/2}$ .

- *minmod:*

$$\text{minmod}(a, b, c) = \begin{cases} \text{argmin}\{|a|, |b|, |c|\} & \text{same sign on all,} \\ 0 & \text{otherwise.} \end{cases}$$

- *Harten's lemma:*

$$\bar{u}_{j+1} = \bar{u}_j + \lambda(C_{j+1/2}\Delta_+\bar{u}_j - D_{j-1/2}\Delta_-\bar{u}_j)$$

is TVD if:

$$\begin{aligned} C_{j+1/2} &\geq 0, \\ D_{j+1/2} &\geq 0, \\ 1 - \lambda(C_{j+1/2} + D_{j+1/2}) &\geq 0. \end{aligned}$$

Proof: Look at  $\sum |\Delta_+\bar{u}_j|$ , observe sum-around.

- *MUSCL scheme:*

$$\hat{u}_{j+1/2}^{(\text{muscl})} = \bar{u}_j + \underbrace{\text{minmod}\left(u_{j+1/2}^{(\text{upwind})} - \bar{u}_j, u_{j+1/2}^{(\text{central})} - \bar{u}_j\right)}_{\bar{u}_{j:=}}$$

Is TVD by Harten's lemma.

Proof: Take

$$\bar{u}_j^{n+1} = \bar{u}_j - \lambda[f(\bar{u}_j + \tilde{u}_j) - f(\bar{u}_{j-1} + \tilde{u}_{j-1})] = \bar{u}_j - \lambda[-D_{j-1/2}\Delta_-\bar{u}_j],$$

and

$$\begin{aligned} D_{j-1/2} &= \frac{f(\bar{u}_j + \tilde{u}_j) - f(\bar{u}_{j-1} + \tilde{u}_{j-1})}{\bar{u}_j - \bar{u}_{j-1}} = f'(\xi) \frac{\bar{u}_j - \bar{u}_{j-1} + \tilde{u}_j - \tilde{u}_{j-1}}{\bar{u}_j - \bar{u}_{j-1}} \\ &= f'(\xi) \left[ 1 + \underbrace{\frac{\tilde{u}_j}{\bar{u}_j - \bar{u}_{j-1}}}_{0 \leq \cdot \leq \frac{1}{2}} - \underbrace{\frac{\tilde{u}_{j-1}}{\bar{u}_j - \bar{u}_{j-1}}}_{0 \leq \cdot \leq \frac{1}{2}} \right] \geq 0 \end{aligned}$$

CFL restriction:  $\lambda \max |f'| \leq 2/3$ .

Now lift wind-from-left restriction.

- General form:

$$\bar{u}_j^{n+1} = \bar{u}_j^n - \lambda \left[ \hat{f}(u_{j+1/2}^-, u_{j+1/2}^+) - \hat{f}(u_{j-1/2}^-, u_{j-1/2}^+) \right],$$

where  $\hat{f}(\uparrow, \downarrow)$  is a monotone flux.

- Now choose

$$u_{j+1/2}^{+, \text{mod}} = \bar{u}_j + \text{minmod}(u_{j+1/2}^+, \bar{u}_j - \bar{u}_{j-1}, \bar{u}_{j+1} - \bar{u}_j)$$

etc.

- Prove TVD by

$$\bar{u}_j^{n+1} = \bar{u}_j^n - \lambda \left[ \underbrace{\hat{f}(u_{j+1/2}^-, u_{j+1/2}^+) - \hat{f}(u_{j+1/2}^-, u_{j-1/2}^+)}_{C_{j+1/2} \Delta_+ \text{-term}} + \underbrace{\hat{f}(u_{j+1/2}^-, u_{j-1/2}^+) - \hat{f}(u_{j-1/2}^-, u_{j-1/2}^+)}_{D_{j-1/2} \Delta_- \text{-term}} \right]$$

using Harten, monotonicity of the flux.

- Smooth and monotone region  $\rightarrow$  high-order accuracy.

Proof:

$$\begin{aligned} \tilde{u}_j &= u_x \frac{\Delta x}{2} + O(\Delta x^2) \\ \bar{u}_{j+1} - \bar{u}_j &= u_x \Delta x + O(\Delta x^2) \\ \bar{u}_j - \bar{u}_{j-1} &= u_x \Delta x + O(\Delta x^2) \end{aligned}$$

So the high-accuracy term is half as big as the low-accuracy limiting terms in the minmod.

- *TVD schemes are at most first-order accurate near smooth extrema.* Consider extremal hump between two grid points.
- *TVB scheme:*

$$\overline{\text{minmod}}(a, b, c) := \begin{cases} a & |a| \leq M |\Delta x|^2, \\ \text{minmod}(a, b, c) & \text{otherwise.} \end{cases}$$

Scheme maintains high-order accuracy, choosing  $M = \frac{2}{3} |u_{x,x}|$ . TVB:

$$\text{TV}(\bar{u}^{n+1}) \leq \text{TV}(\bar{u}^{n+1}) + CM \Delta x^2 N \leq \text{TV}(\bar{u}^n) + C \Delta t.$$

- *Semidiscrete Cell Entropy Inequality:*

$$\frac{dU(u_j)}{dt} + \frac{1}{\Delta x} [\hat{F}_{j+1/2} - \hat{F}_{j-1/2}] = - \frac{1}{\Delta x} \underbrace{\Theta_j}_{\geq 0}.$$

Let  $U''(u) \geq 0$  and integrate by parts in the definition of the entropy flux  $F$ . Let

$$\hat{F}_{j+1/2} = U'(u_j) \hat{f}(u_j, u_{j+1}) - \int^{u_j} U''(u) f(u) du.$$

Multiply the c.law by  $U'(u_j)$ , yielding a “junk” term  $\Theta_j$  that ends up being positive, proving the CEI.

### 3.2 ENO/WENO

- *Newton interpolation:*

$$\begin{aligned} y[x_i] &= y_i, \\ y[x_i, x_{i+1}] &= \frac{y[x_{i+1}] - y[x_i]}{x_{i+1} - x_i}, \\ y[x_i, x_{i+1}, x_{i+2}] &= \frac{y[x_{i+1}, x_{i+2}] - y[x_i, x_{i+1}]}{x_{i+2} - x_i}, \end{aligned}$$

then

$$p(x) = y[x_0] + y[x_0, x_1](x - x_0) + y[x_0, x_1, x_2](x - x_0)(x - x_1) + \dots$$

- *Interpolation ↔ Reconstruction:* Thinking about  $P = \int p$ , where  $p$  is the reconstruction polynomial, yields that running sums of cell averages turn reconstruction into interpolation. Since the step  $P \rightarrow p$  is first differences, i.e. undoing running sums, the reconstruction polynomial for  $\bar{u}$  is the same as the interpolation polynomial for  $\sum \bar{u}$ .
- *ENO idea:* Progressively expand the stencil in the direction with the lowest divided differences. Un-divided differences (for a uniform mesh) may be precomputed.
- *WENO idea:* Start with a linear combination of smaller stencils that gives high-order accuracy.

$$\sum_i \alpha_i \text{stencil}_i$$

Now weight them so that  $w_i = \alpha_i + O(\Delta x^2)$  in smooth regions and  $w_i = O(\Delta x^4)$ . The normalize the  $w_i$  so they add up to one.

### 3.3 Finite Differences

- *Finite Difference Idea:* View  $f(u_j)$  as cell averages of a function  $h$ . Then

$$f(u)_x = \frac{1}{\Delta x} [h(x + \Delta x/2) - h(x - \Delta x/2)].$$

So do reconstruction on values of  $f(u_j)$ .

- *Flux splitting:* Required to show stability using Harten.

$$\hat{f}_{j+1/2} = \hat{f}_{j+1/2}^+(u^-) + \hat{f}_{j+1/2}^-(u^+).$$

Assumptions:

- $\frac{d\hat{f}^+}{du} \geq 0$ ,
- $\frac{d\hat{f}^-}{du} \leq 0$ .

Lax-Friedrichs is a splittable flux.

- *Limiting/stability:* Focus on  $\hat{f}^+$  for now.

$$\hat{f}_{j+1/2}^{+, \text{mod}} = f(u_j) + \min(\text{mod}(\hat{f}_{j+1/2}^{+, \text{orig}}, \Delta_+ f(u_j), \Delta_- f(u_j)))$$

- *Scheme:*

$$u_t = (\hat{f}_{j+1/2}^+ + \hat{f}_{j+1/2}^-) - (\hat{f}_{j-1/2}^+ + \hat{f}_{j-1/2}^-)$$

- *Mesh must be uniform or smoothly mappable to uniform. WHY?*

## 4 Numerics in Multiple Space Dimensions

- $u_t + f(u)_x + g(u)_y = 0$ .

- Weak solutions, entropy solutions same as 1D.
- Motone schemes have the same properties (TVD, entropy condition,  $L^1$  contraction.
- *TVD schemes are at most first order.*  
“Proof”: Consider a wiggly jump vs. a straight jump. One has high TV, the other low.
- Saying TVD in  $n$ D literature amounts to “TVD in 1D, but straightforwardly generalized to 2D”.
- *Maximum principle*: Consider scheme in Harten form. Then  $u_{i,j}^{n+1}$  is a convex combination of the values on the stencil.
- *Finite-volume*:

$$\begin{aligned} & \frac{1}{\Delta x \Delta y} \int_{y_{j-1/2}}^{y_{j+1/2}} \int_{x_{i-1/2}}^{x_{i+1/2}} f(u) dx dy \\ &= \frac{1}{\Delta x \Delta y} \int_{y_{j-1/2}}^{y_{j+1/2}} f(u(x_{i+1/2}, y, t)) - f(u(x_{i-1/2}, y, t)) dy. \end{aligned}$$

One integral is simple reconstruction, which must be carried out in two directions. Then the second integral must be carried out numerically.

General procedure:

$$\begin{array}{c} \{ \tilde{u}_{i,j} \} \\ \nearrow \text{1D rec} \\ \{ \tilde{u}_{i+1/2,j} \} \xrightarrow{\text{1D rec}} \{ u_{i+1/2,j+w_k} \} \longrightarrow \{ f(u_{i+1/2,j+w_k}) \} \xrightarrow{\text{num.int.}} \{ \hat{f}_{i+1/2,j} \} \\ \searrow \text{1D rec} \\ \{ \tilde{u}_{i,j+1/2} \} \xrightarrow{\text{1D rec}} \{ u_{i+\omega_k,j+1/2} \} \longrightarrow \{ f(u_{i+\omega_k,j+1/2}) \} \xrightarrow{\text{num.int.}} \{ \hat{f}_{i,j+1/2} \} \end{array}$$

Only relevant for third and higher order since

$$\tilde{u}_{i,j} = u(x_i, y_j) + O(\Delta x^2, \Delta y^2),$$

where  $\tilde{\cdot}$  and  $\bar{\cdot}$  are cell averaging in  $x$  and  $y$ .

- *Finite-difference*: Generalizes straightforwardly.

## 5 Systems of Conservation Laws

- *Linear case*:

$$u_t + A u_x = 0$$

$A$  has complete set of eigenvectors and only real eigenvalues, it's called (strongly) hyperbolic.

If constant linear system, use change of variables and use upwind/downwind depending on sign of eigenvalue.  $A^+ = R \Lambda^+ R^{-1} \neq A^+$ , elementwise.

- If nonlinear, then find eigenvalues for each new matrix  $\nabla \mathbf{f}(\mathbf{u})$ , transform to diagonal form, carry out scalar reconstruction, then transform back.  
Rationale: Separation of shocks—two shocks travelling at different speeds.
- All results about stability and convergence carry over to linear systems using the characteristic procedure above.
- Steps for the nonlinear case:
  - At  $x_{j+1/2}$  find a crude “reference vector”  $\tilde{u}_{j+1/2}$  as
    - $\tilde{u}_{j+1/2} = \frac{1}{2}(\bar{u}_j + \bar{u}_{j+1})$
    - or *Roe average*:  $f(\bar{u}_{j+1}) - f(\bar{u}_j) = f'(\tilde{u}_{j+1/2})(\bar{u}_{j+1} - \bar{u}_j)$



- Diagonalize  $f'(\tilde{u}_{j+1/2}) = R \Lambda R^{-1}$ .
- Transform all involved cell averages using  $\bar{v} = R^{-1} \bar{u}$ .
- Carry out 1D reconstruction.
- Recover  $u_{j+1/2} = R v_{j+1/2}$ .
- For 2D nonlinear system, combine system approach with 2D stuff above.

## 6 Discontinuous Galerkin

- *Derivation of the Scheme:* Multiply PDE by test function  $v$ , integrate by parts, interpret arising boundary terms by comparing with FV, using  $v = \mathbf{1}_{I_j}$ . This gives

$$\int_{I_j} u_t v - \int_{I_j} f(u) v_x + \hat{f}(u_{j+1/2}^-, u_{j+1/2}^+) - \hat{f}(u_{j-1/2}^-, u_{j+1/2}^+) = 0.$$

Then pick a basis in the space  $V_h$